# Homework 8

Math 25b

Due April 11, 2018

Topics covered: Fubini's theorem, partitions of unity, diffeomorphisms

Instructions:

- The homework is divided into one part for each CA. You will submit each part to the corresponding CA's mailbox on the second floor of the science center.
- If your submission to any one CA takes multiple pages, then staple them together. A stapler is available in the Cabot library in the science center.
- If you collaborate with other students, please mention this near the corresponding problems.
- Most problems from this assignment come from Spivak's *Calculus* or Spivak's *Calculus on manifolds* or Munkres' *Analysis on manifolds*. I've indicated this next to the problems (e.g. Spivak, CoM 1-2 means problem 2 of chapter 1 from Calculus on Manifolds).
- Any result that we proved in class can be freely used on the homework. If there's a result that we haven't stated in class that you want to use, then you have to prove it. If there's a result that we stated in class, but haven't proven, it's best to ask for clarification.

# 1 For Ellen

**Problem 0.** One of the problems on this assignment has a part that asks you to show something that's false. You'll need to find it. In your solution you should explain why it's false. Good luck!

**Problem 1** (Munkres, 12-2). Let  $Q = [0,1] \times [0,1]$ . Define  $f : Q \to \mathbb{R}$  by

$$f(x,y) = \begin{cases} 1/q & y \in \mathbb{Q} \text{ and } x = p/q \text{ lowest terms} \\ 0 & else \end{cases}$$

- (a) Does  $\int_{O} f$  exist? Explain.
- (b) Compute  $\underline{\int}_{y \in I} f(x, y)$  and  $\overline{\int}_{y \in I} f(x, y)$ .
- (c) Verify Fubini's theorem.

Solution.

**Problem 2** (Spivak, CoM 3-28 and Munkres, 12-4 and Hubbard, 4.5.11). Consider  $f : \mathbb{R}^2 \to \mathbb{R}$ .

- (a) Use Fubini's theorem to give an easy proof that  $D_1D_2f = D_2D_1f$  if these are continuous (Clairaut's theorem).
- (b) The function

$$f(x,y) = \begin{cases} xy \frac{x^2 - y^2}{x^2 + y^2} & (x,y) \neq (0,0) \\ 0 & otherwise \end{cases}$$

is the standard example of a function that is twice-differentiable but  $D_1D_2(f) \neq D_2D_1(f)$  at 0 (you showed this in HW4). Where does the proof of (a) fail in this case?<sup>1</sup>

Solution.

**Problem 3** (Spivak, CoM 3-26). Let  $f : [a,b] \to \mathbb{R}$  be bounded, integrable, and non-negative. Let  $A = \{(x,y) : a \le x \le b \text{ and } 0 \le y \le f(x)\}$ . Show that A is rectifiable and has area  $\int_a^b f$ . Hint: most of the work goes toward showing that A is rectifiable. Warning: f is not assumed to be continuous!

Solution.

<sup>&</sup>lt;sup>1</sup>You might enjoy computing the partial derivatives with Mathematica or Wolfram Alpha.

# 2 For Charlie

Problem 4 (Spivak, CoM 3-29).

- (a) Use Fubini's theorem to derive the volume of a cone C with base r and height h.
- (b) Fix  $a \ge 0$ , and let  $f : [a,b] \to \mathbb{R}$  and  $g : [a,b] \to \mathbb{R}$  be continuous functions such that  $f(z) \le g(z)$  for each  $z \in [a,b]$ . Consider  $S = \{(y,z) : f(z) \le y \le g(z) \text{ and } a \le z \le b\}$ . Derive an expression for the volume of a set  $C \subset \mathbb{R}^3$  obtained by revolving S about the z-axis.
- (c) Repeat (b) but now with f, g functions of y, i.e.  $S = \{(y,z) : a \le y \le b \text{ and } f(y) \le z \le g(y)\}$ . (Again revolving S around the z-axis.)<sup>2</sup>

Solution.

**Problem 5** (Spivak, CoM 3-30). Let C be the set constructed in HW3#3. Show that

$$\int_{y \in [0,1]} \left( \int_{x \in [0,1]} \chi_C(x,y) \right) = \int_{x \in [0,1]} \left( \int_{y \in [0,1]} \chi_C(x,y) \right) = 0$$

but that  $\int_{[0,1]\times[0,1]} \chi_C$  does not exist.

#### Solution.

Problem 6 (Spivak, CoM 3-36). In this problem you prove Cavalieri's principle.

- (a) Let A and B be rectifiable subsets of  $\mathbb{R}^3$ . Let  $A_c = \{(x, y) : (x, y, c) \in A\}$  and define  $B_c$  similarly. Suppose  $A_c$  and  $B_c$  are rectifiable and have the same area for each c. Show that A and B have the same volume.<sup>3</sup>
- (b) Look up the "napkin-ring problem," which is a popular application of Cavalieri's principle. Explain it to your friends.

Solution.

<sup>&</sup>lt;sup>2</sup>In multivariable calculus, these two methods of computing volumes of revolution are typically called the "shell" and the "washer" methods.

<sup>&</sup>lt;sup>3</sup>See pictures on the course webpage.

# 3 For Natalia

Problem 7 (Munkres, 16-1). In this problem you will show

$$f(x) = \begin{cases} e^{-1/x} & x > 0\\ 0 & x \le 0. \end{cases}$$

is smooth  $f : \mathbb{R} \to \mathbb{R}$ .<sup>4</sup>

- (a) Show that  $x < e^x$  for all  $x \in \mathbb{R}$ . Hint: use the power series definition.
- (b) Prove that f is continuous at 0.
- (c) Prove that f is differentiable at 0 and f'(0) = 0. Hint: L'Hopital. It might help to write  $\frac{e^{-1/x}}{r} = \frac{1/x}{e^{1/x}}$ .
- (d) For each  $k \ge 1$  the functions  $f^{(k)}(x)$  are linear combinations of the functions  $\frac{1}{x^n}e^{-1/x}$  on  $(0,\infty)$ . Conclude that f is smooth on  $(0,\infty)$ .
- (e) Show that  $\lim_{x\to 0+} \frac{1}{x^n} e^{-1/x} = 0$  for every  $n \ge 1$ . Conclude that  $f^{(k)}(0) = 0$  for every k.

Solution.

**Problem 8** (Spival 2-26). Let h(x) = f(x)f(1-x), where f is the function from the previous problem. Observe that  $h : \mathbb{R} \to \mathbb{R}$  is smooth and that h is positive on (0, 1) and 0 elsewhere.

- (a) Show that there is a smooth function  $g : \mathbb{R} \to [0,1]$  such that g(x) = 0 for  $x \le 0$  and g(x) = 1for  $x \ge \epsilon$ . Hint: if  $\phi$  is a smooth function that is positive on  $(0,\epsilon)$  and 0 otherwise, consider  $g(x) = \int_0^x \phi / \int_0^\epsilon \phi$ .
- (b) If  $a \in \mathbb{R}^n$ , define  $\phi : \mathbb{R}^n \to \mathbb{R}$  by

$$\phi(x) = h(\frac{x_1 - a_1}{\epsilon}) \cdot \ldots \cdot h(\frac{x_n - a_n}{\epsilon}).$$

Show that g is smooth, positive on  $Q = (a_1, a_1 + \epsilon) \times \cdots \times (a_n, a_n + \epsilon)$ , and zero elsewhere.

- (c) If  $A \subset \mathbb{R}^n$  is open and  $C \subset A$  is compact, show that there is a non-negative smooth function  $\phi : A \to \mathbb{R}$  such that  $\phi(x) > 0$  for  $x \in C$  and  $\phi = 0$  outside of some closed set contained in A.
- (d) Show that we can choose such an  $\phi$  so that  $\phi : A \to [0,1]$  and  $\phi(x) = 1$  for  $x \in C$ . Hint: Compose the function from (c) by the function from (a) with a smart choice of  $\epsilon$ .

Solution.

<sup>&</sup>lt;sup>4</sup>We haven't given a formal treatment to exponential functions, although you probably know some basic properties about them. One rigorous definition is  $e^x = \sum_{n=0}^{\infty} \frac{x^n}{n!}$ . (One can show that this series converges for every x.) From this definition one can deduce some familiar properties like  $e^0 = 1$  and  $e^x \cdot e^y = e^{x+y}$ . A different characterization/definition of  $e^x$  is as the unique solution of the differential equation f' = f with initial condition f(0) = 1 (c.f. Extra Credit 2).

### 4 For Michele

**Problem 9** (Munkres, 16-3). Fix any  $S \subset \mathbb{R}^n$  and fix  $y \in S$ . Say that a function  $f : S \to \mathbb{R}$  is continuously differentiable at y if there is a  $C^1$  function  $g : U \to \mathbb{R}$  defined in a neighborhood of y in  $\mathbb{R}^n$  such that g agrees with f on  $U \cap S$ .

(a) Suppose  $f : S \to \mathbb{R}$  is continuously differentiable at y. Show that if  $\phi : \mathbb{R}^n \to \mathbb{R}$  is a  $C^1$  function whose support lies in U, then the function

$$h(x) = \begin{cases} \phi(x)g(x) & x \in U\\ 0 & x \notin supp(\phi) \end{cases}$$

is a well-defined  $C^1$  function on  $\mathbb{R}^n$ .

(b) Prove: If  $f: S \to \mathbb{R}$  is continuously differentiable at each  $y \in S$ , then f may be extended to a  $C^1$  function  $h: A \to \mathbb{R}$  defined on an open set containing S. Hint: this is a gluing problem.

Solution.

**Problem 10** (Spivak, CoM 3-40). Fix  $g : \mathbb{R}^n \to \mathbb{R}^n$ , and suppose  $a \in \mathbb{R}^n$  satisfies det  $Dg(a) \neq 0$ .

- (a) Prove that in some open set containing a we can write  $g = T \circ f_n \circ \cdots \circ f_1$ , where  $f_i$  is of the form  $f_i(x) = (x_1, \ldots, \phi_i(x), \ldots, x_n)$ , and T is a linear map. Hint: Use the map T to replace g by a function whose derivative at a is the identity.
- (b) Show that we can write  $g = g_n \circ \cdots \circ g_1$  if and only if Dg(a) is a diagonal matrix.

Solution.