## Homework 4

Math 25a

Due October 12, 2018

Topics covered (lecture 8): linear maps, kernel/image
Instructions:

- The homework is divided into one part for each CA. You will submit each part to the corresponding CA's mailbox on the second floor of the science center.
- If your submission to any one CA takes multiple pages, then staple them together. A stapler is available in the Cabot library in the science center.
- If you collaborate with other students, please mention this near the corresponding problems.
- Some problems from this assignment come from the 3rd edition of Axler's book. I've indicated this next to the problems. For example, Axler 1.B. 4 means problem 4 from the exercises to Section B of Chapter 1. Sometimes the problem in Axler is slightly different, so make sure you do the problem as listed in the assignment.


## 1 For Beckham

Problem 1 (Axler 3.A.7). Suppose that $V$ is 1-dimensional. Show that for every linear map $T: V \rightarrow V$ there exists $a \in F$ so that $T v=a v$ for all $v \in V$.

## Solution.

Problem 2. Let $T: \mathbb{R}^{n} \rightarrow \mathbb{R}^{m}$ be a linear map. Show that if $z$ is the midpoint of the line segment $[x, y]$ between $x, y \in \mathbb{R}^{n}$, then $T(z)$ is the midpoint of $[T(x), T(y)]$. Hint: give a formula for the midpoint of a line segment in terms of the endpoints.

Problem 3. Consider the bijection $\mathbb{C} \rightarrow \mathbb{R}^{2}$ defined by $x+i y \mapsto(x, y)$. Under this bijection, we can treat $\mathbb{C}$ either as a 1-dimensional complex vector space or as a 2 -dimensional real vector space.
(a) Treating $\mathbb{C}$ as a complex vector space, show that the multiplication by $\alpha=a+i b \in \mathbb{C}$ is $a$ linear transformation of $\mathbb{C}$. What is its matrix? ${ }^{1}$
(b) Treating $\mathbb{C}$ as the real vector space $\mathbb{R}^{2}$, show that the multiplication by $\alpha=a+i b$ is a linear map. What is its matrix?
(c) Define $T(x+i y)=2 x-y+i(x-3 y)$. Show that $T$ does not define a linear map $\mathbb{C} \rightarrow \mathbb{C}$ (viewed as a complex vector space), but it does define a linear map $\mathbb{R}^{2} \rightarrow \mathbb{R}^{2}$

Solution.

[^0]
## 2 For Davis

Problem 4 (Axler 3.A.8). Give an example of a function $f: \mathbb{R}^{2} \rightarrow \mathbb{R}$ such that $f(a v)=a f(v)$ for all $a \in \mathbb{R}$ and all $v \in \mathbb{R}^{2}$ but $f$ is not linear.

Solution.
Problem 5 (Axler 3.B.9-10). Let $T: V \rightarrow W$ be a linear map.
(a) Show that if $T$ is injective and $v_{1}, \ldots, v_{n}$ are linearly independent in $V$, then $T v_{1}, \ldots, T v_{n}$ are linearly independent in $W$.
(b) Show that if $T$ is surjective and $v_{1}, \ldots, v_{n}$ span $V$, then $T v_{1}, \ldots, T v_{n}$ span $W$.

Solution.
Problem 6. Consider $T: \mathbb{R}^{2} \rightarrow \mathbb{R}$ defined by $T(x, y)=x+y$. Find all the linear maps $S: \mathbb{R} \rightarrow \mathbb{R}^{2}$ so that $T S=I$ (here I refers to the identity map $\mathbb{R} \rightarrow \mathbb{R}$ ).

Solution.

## 3 For Joey

Problem 7 (Axler 3.B.20-21). Assume $W$ is finite dimensional and $T: V \rightarrow W$ is linear. ${ }^{2}$
(a) Show that if $T$ is injective, then there exists a linear map $S: W \rightarrow V$ so that $S T=I_{V}$.
(b) Show that if $T$ is surjective, then there exists a linear map $S: W \rightarrow V$ so that $T S=I_{V}$.

## Solution.

Problem 8. Write a formula for each of the maps $\mathbb{R}^{3} \rightarrow \mathbb{R}^{3}$, and verify that they are linear.
(a) Project every vector onto the xy-plane.
(b) Reflect every vector through the $x y$-plane.
(c) Rotate the $x y$-plane by $\pi / 6$, leaving the $z$-axis fixed.

Problem 9. Work out the kernel of the derivative map $D: \operatorname{Poly}(F) \rightarrow \operatorname{Poly}(F)$ when $F=\mathbb{Z} / 2 \mathbb{Z}$. What happens for $F=\mathbb{Z} / p \mathbb{Z}$ ? ${ }^{3}$

Solution.

[^1]
## 4 For Laura

Problem 10 (Axler 3.B.5). Give an example of a linear map $T: \mathbb{R}^{4} \rightarrow \mathbb{R}^{4}$ such that $\operatorname{Im} T=\operatorname{ker} T$.

## Solution.

Problem 11. Let Poly $(F)$ be the vector space of all polynomials with coefficients in $F$, and let $V=$ Fun $(F, F)$ be the vector space of all functions $f: F \rightarrow F$. Define a map of sets $T: \operatorname{Poly}(F) \rightarrow V$ by $T(p)(a)=p(a)$ the function mapping $a \in F$ to $p(a) \in F$.
(a) Show that $T$ is a linear map.
(b) For $F=\mathbb{R}$ show that $T$ is injective but not surjective.
(c) Give an example of a field $F$ where $T$ is surjective but not injective, and prove your claim.

Solution.
Problem 12. Let $F=\mathbb{Z} / p \mathbb{Z}$ for a prime number $p$. What is the probability that a linear map $T: F^{2} \rightarrow F^{2}$ is a linear isomorphism when randomly choosing out of all such maps? (Note that a linear isomorphism sends a basis of $F^{2}$ to another basis of $F^{2}$ by another problem on this assignment.) As p increases is one more or less likely to choose a linear isomorphism at random?

Solution.


[^0]:    ${ }^{1}$ We'll discuss matrices in the next lecture, but I think you can figure this out before then.

[^1]:    ${ }^{2}$ Compare this with a similar problem from HW1. The key is to define $S$ so that it is linear. Not every $S$ works!
    ${ }^{3}$ The derivative is the linear map defined on the standard basis by $D\left(x^{i}\right)=i \cdot x^{i-1}$.

